

# Evaluating offshore wind resources and ecological conditions in Lake Michigan with a NOMAD buoy and laser sensor

Erik Nordman, Ph.D.  
*Grand Valley State University*

*with*

A. Boezaart

J. Edmonson

Y. Nieves

N. Pervez

A. Rahman, Ph.D.

M. Sozen, Ph.D.

C. Standridge, Ph.D.

D. Zeitler, Ph.D.

G. Meadows, Ph.D. (Northern Michigan University)



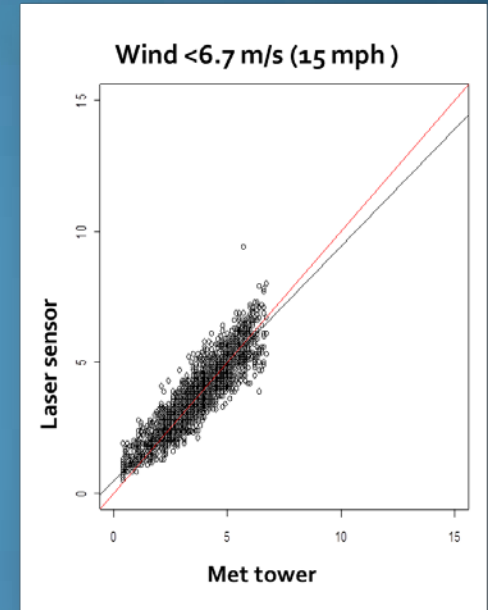
# Are floating, laser-pulse sensors an effective alternative to offshore, tower-mounted anemometers?



The need for new measurement tools



Deployment and analysis



Validation of floating sensor

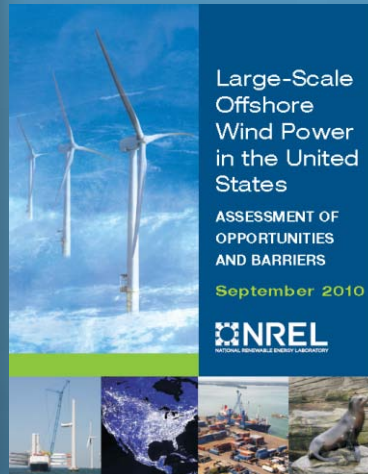
# Offshore tower-mounted anemometers are costly to construct. Alternative systems are needed.

Offshore met tower costs range from \$2.5 million to \$10 million

Deep water particularly expensive



Source: Noordzeewind



DOE: Need on-site measurements

- Validate models
- Support projects
- Existing buoys ill-suited
- *New technologies must be verified*



Floating, laser pulse sensors have the potential to resolve some of the DOE's challenges, but must be validated.

Laser sensor



The Vindicator

- Laser pulse
- 6 range gates
- Motion compensation
- 1 second data
- Gauge precision = 0.1 m/s

Acoustic monitors



Self-powered:  
wind, solar,  
diesel

Floating platform:  
Nomad buoy

Water quality  
sensors

We tested the WindSentinel buoy from AXYS Technologies

# The validation protocol consisted of two comparisons.

Previous studies have validated the operation of laser (LiDAR) sensors using co-located tower anemometers.

## 1. Compare laser sensors

- Buoy-mounted
- Land-based



## 2. Compare:

- Buoy-mounted laser sensor
- Land-based anemometer



## Validation criteria

Mean differences are...

- not operationally significant ( $< 0.1$  m/s)
- not statistically significant ( $p > 0.05$ )

# A comparison of fixed and buoy-mounted laser units found no operationally significant differences.



Race Rocks, BC  
Two Vindicator units

- 3 range gates
- 700 m apart
- Data collected by buoy manufacturer, analyzed by GVSU

Paired *t*-tests,  $n = 3022$

Height	Mean difference	SD
100 m	0.13* m/s	0.48
150 m	0.08* m/s	0.48
200 m	0.07* m/s	0.48

\* $p < 0.05$

Validation criteria

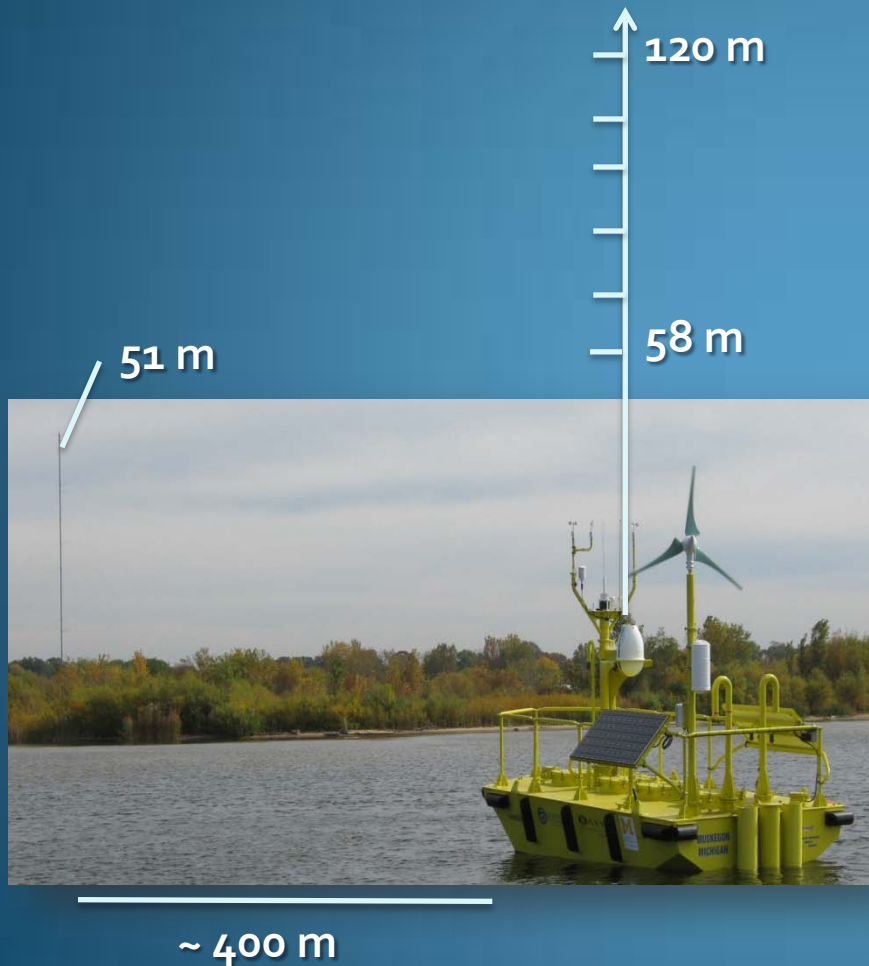
Mean differences are...

- Not operationally significant
- Not statistically significant



**Conclusion: motion compensation works**

The research team validated buoy measurements using an onshore anemometer.



## Field trial

Muskegon Lake, Michigan  
October 7 – November 3, 2011  
10 minute average data  
Gauge precision = 0.1 m/s

2 wind regimes



Calm  
 $< 6.7$  m/s



Windy  
 $> 6.7$  m/s

3 storm events were removed from the dataset.



The buoy was placed about 400 m offshore from the met tower at the east end of Muskegon Lake.







On calm days, the measurement differences were not operationally significant.

Calm days <6.7 m/s

Paired  $t$ -test,  $n = 2149$

Mean difference =  $-0.10^* (0.58)$

$*p < 0.05$

Validation criteria

Mean differences are...

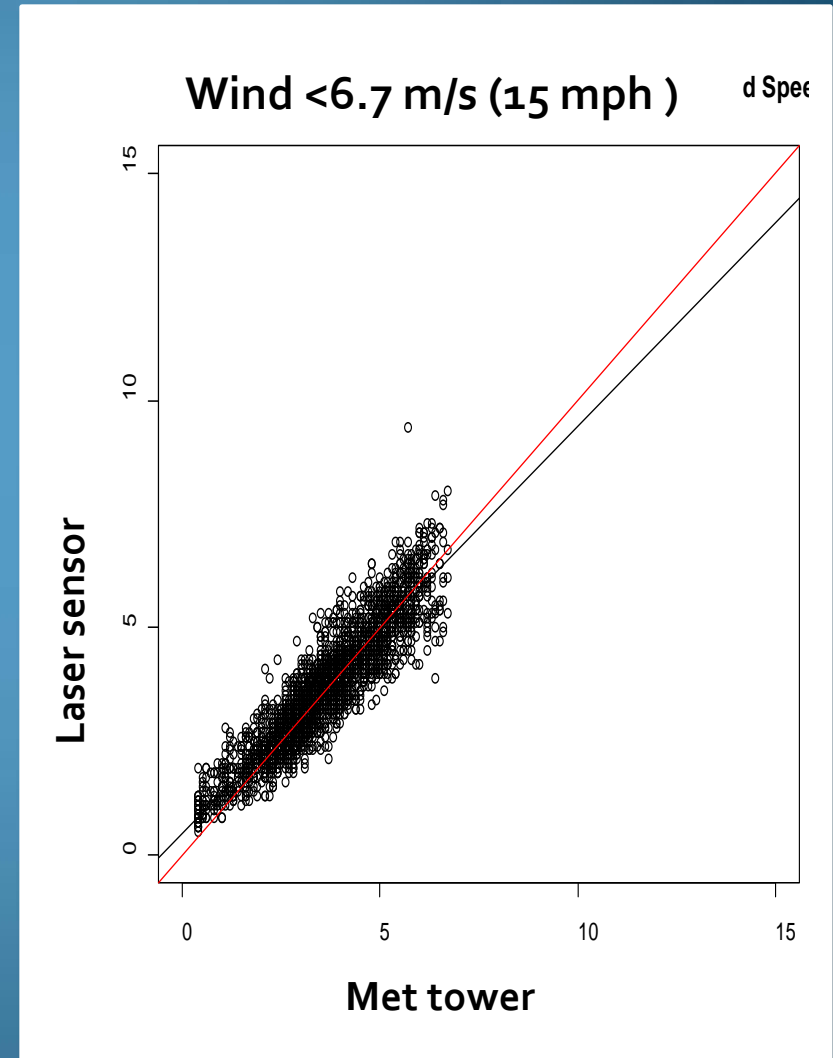
- Not operationally significant



- Not statistically significant



Conclusion: On calm days, laser as accurate as anemometer.





On windy days, the measurement differences were not statistically or operationally significant.

Windy days  $>6.7$  m/s, no storms

Paired  $t$ -test,  $n = 416$

Mean difference =  $-0.03$  m/s (1.09)

$p > 0.05$

Validation criteria

Mean differences are...

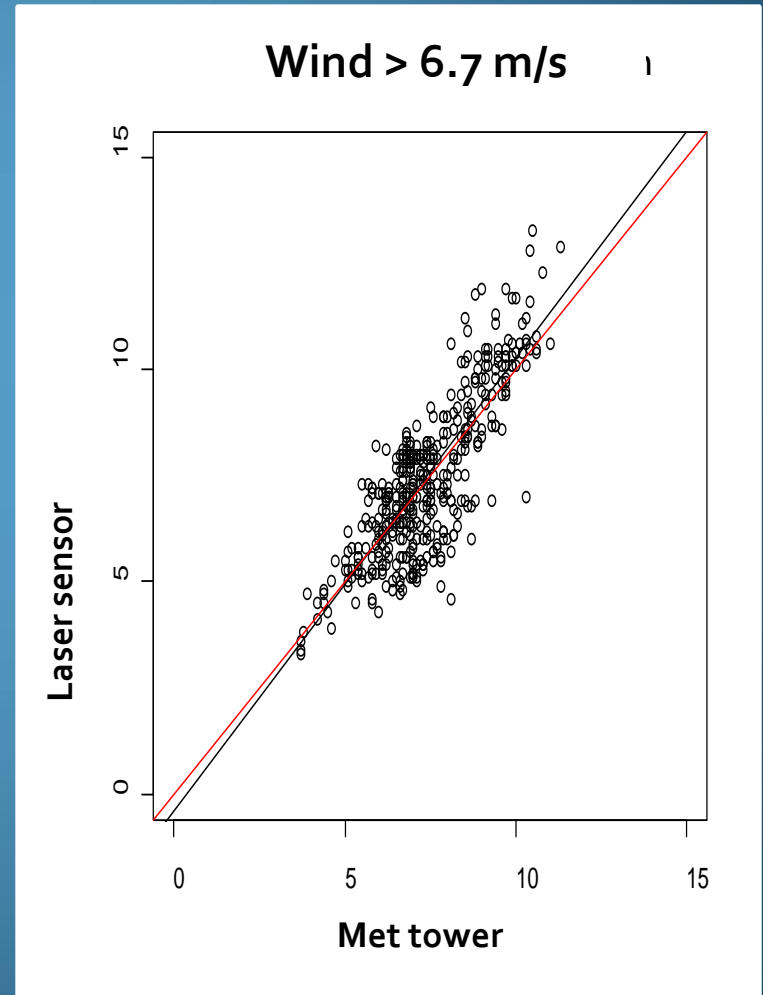
- Not operationally significant



- Not statistically significant



Conclusion: On windy days, laser as accurate as anemometer.



# Buoy-mounted laser sensors show promise as an alternative to offshore met towers.

Under most conditions, the measured wind speed differences were not operationally significant.

Race Rocks (two laser sensors)

- Differences not operationally significant



Muskegon Lake

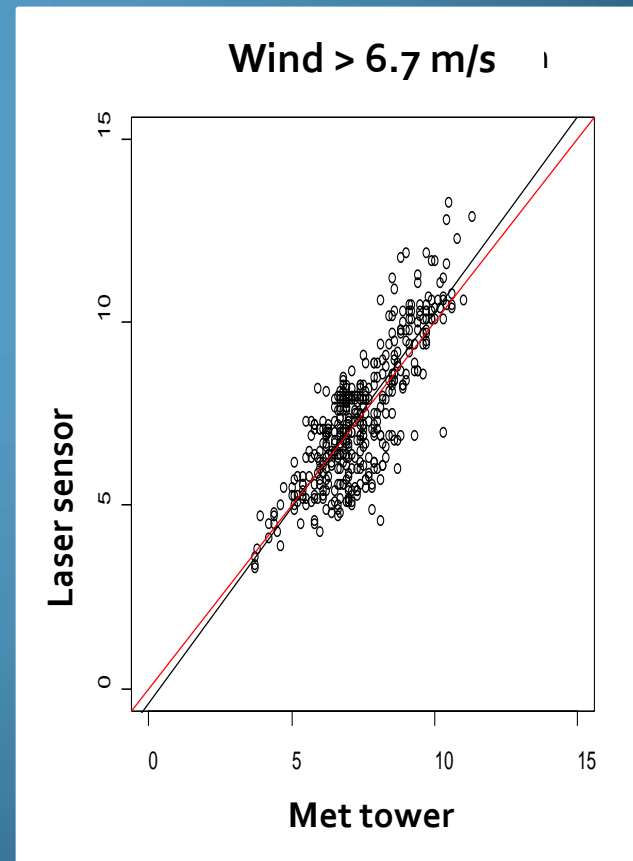
*Calm days*

- Differences not operationally significant



*Windy days*

- Differences not operationally or statistically significant





# The research buoy is now deployed at Lake Michigan's Mid-Lake Plateau.



Data images source: Corbis Images

Collecting data on:



Wind



Birds



Bats

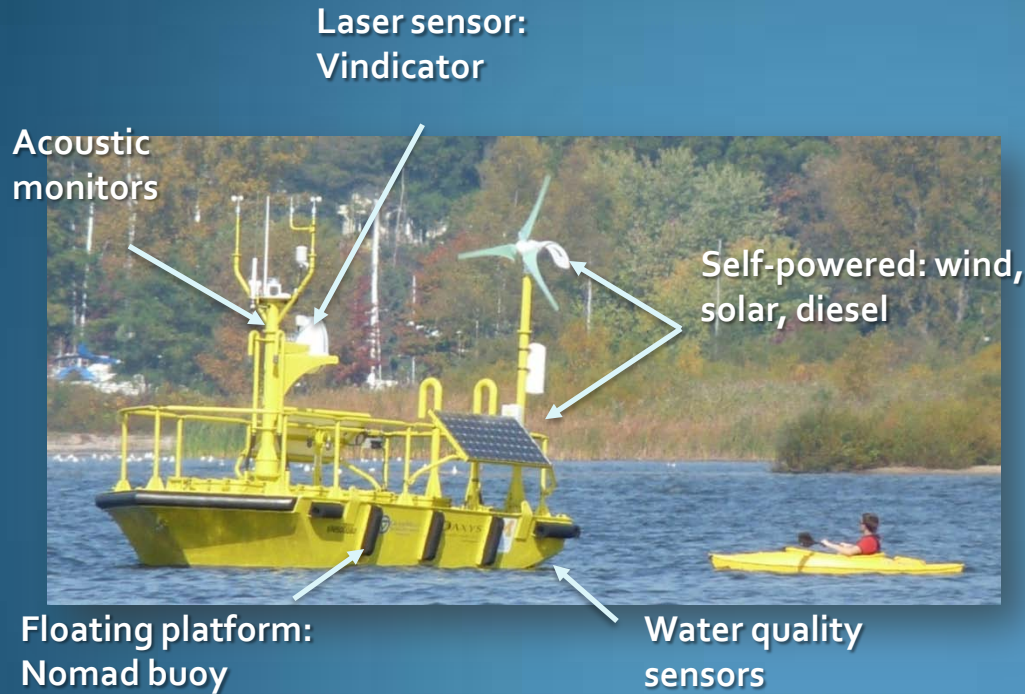


Water  
(biological)

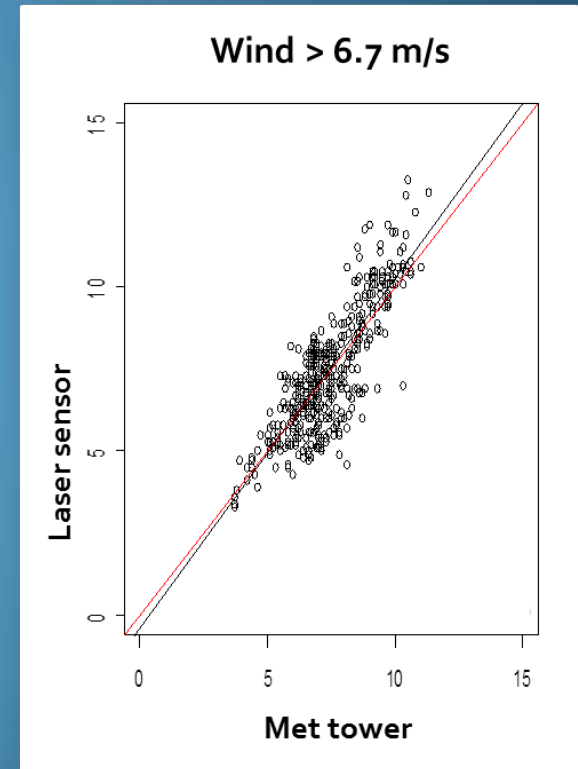


Water  
(physical)

# Thank you for this opportunity.



Email: [nordmane@gvsu.edu](mailto:nordmane@gvsu.edu)



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